

MF10

Universal Monolithic Dual Switched Capacitor Filter

General Description

The MF10 consists of 2 independent and extremely easy to use, general purpose CMOS active filter building blocks. Each block, together with an external clock and 3 to 4 resistors, can produce various 2nd order functions. Each building block has 3 output pins. One of the outputs can be configured to perform either an allpass, highpass or a notch function; the remaining 2 output pins perform lowpass and bandpass functions. The center frequency of the lowpass and bandpass 2nd order functions can be either directly dependent on the clock frequency, or they can depend on both clock frequency and external resistor ratios. The center frequency of the notch and allpass functions is directly dependent on the clock frequency, while the highpass center frequency depends on both resistor ratio and clock. Up to 4th order functions can be performed by cascading the two 2nd order building blocks of the MF10; higher than 4th order functions can be obtained by cascading MF10 packages.

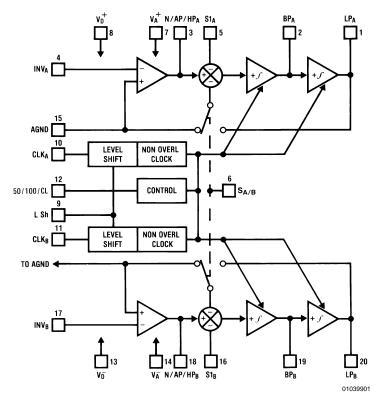
Any of the classical filter configurations (such as Butterworth, Bessel, Cauer and Chebyshev) can be formed.

For pin-compatible device with improved performance refer to LMF100 datasheet.

Features

- Easy to use
- Clock to center frequency ratio accuracy ±0.6%
- Filter cutoff frequency stability directly dependent on external clock quality
- Low sensitivity to external component variation
- Separate highpass (or notch or allpass), bandpass, lowpass outputs
- f_O x Q range up to 200 kHz
- Operation up to 30 kHz
- 20-pin 0.3" wide Dual-In-Line package
- 20-pin Surface Mount (SO) wide-body package

System Block Diagram



Package in 20 pin molded wide body surface mount and 20 pin molded DIP.

Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

| Supply Voltage (V ⁺ – V ⁻) | 14V |
|---|----------------|
| Voltage at Any Pin | $V^{+} + 0.3V$ |
| | $V^{-} - 0.3V$ |
| Input Current at Any Pin (Note 2) | 5 mA |
| Package Input Current (Note 2) | 20 mA |
| Power Dissipation (Note 3) | 500 mW |
| Storage Temperature | 150°C |
| ESD Susceptability (Note 11) | 2000V |

Soldering Information

N Package: 10 sec 260°C

SO Package:

 Vapor Phase (60 Sec.)
 215°C

 Infrared (15 Sec.)
 220°C

See AN-450 "Surface Mounting Methods and Their Effect on Product Reliability" (Appendix D) for other methods of soldering surface mount devices.

Operating Ratings (Note 1)

| Temperature Range | $T_{MIN} \le T_A \le T_{MAX}$ |
|-------------------|--|
| MF10ACN, MF10CCN | $0^{\circ}C \leq T_{A} \leq 70^{\circ}C$ |
| MF10CCWM | $0^{\circ}C \leq T_{A} \leq 70^{\circ}C$ |

Electrical Characteristics

 $V^+ = +5.00V$ and $V^- = -5.00V$ unless otherwise specified. **Boldface limits apply for T_{MIN} to T_{MAX}**; all other limits T_A = T_J = 25°C.

| | | | | | MF10 | | | |
|----------------------------------|------------------------------------|---------------------|--------------------------|--|--------------|-------------|--------------|-----|
| | | | MF10CCWM | | | | | |
| Symbol | Parameter | Cond | Typical (Note 8) | Tested Limit | Design Units | Units | | |
| | | | | | | (Note 9) | (Note 10) | |
| V+ - V- | Supply Voltage | Supply Voltage Min | | | | | 9 | V |
| | | Max | | | | | 14 | V |
| I _S | Maximum Supply | Clock Applied 11 | 8 | 12 | 12 | mA | | |
| | Current | | No Input Signal | | | | | |
| f_O | Center Frequency | Min | f _O x Q < 200 | f _O x Q < 200 kHz | | | 0.2 | Hz |
| | Range | Max | | | | | 20 | kHz |
| f_{CLK} | Clock Frequency | Min | | | | | 10 | Hz |
| | Range | Max | | | 1.5 | | 1.0 | MHz |
| f_{CLK}/f_{O} | 50:1 Clock to Center Frequency | MF10A | Q = 10 Mode 1 | $V_{pin12} = 5V$ $f_{CLK} = 250$ | ±0.2 | ±0.6 | ±0.6 | % |
| | Ratio Deviation | MF10C | KHz | | ±0.2 | ±1.5 | ±1.5 | % |
| f _{CLK} /f _O | 100:1 Clock to Center Frequency | MF10A | Q = 10 Mode 1 | PIII12 | | ±0.6 | ±0.6 | % |
| | Ratio Deviation | MF10C | Wode 1 | f _{CLK} = 500 kHz | ±0.2 | ±1.5 | ±1.5 | % |
| | Clock Feedthrough | | Q = 10 Mode 1 | | 10 | | | mV |
| | Q Error (MAX) | | Q = 10 | $V_{pin12} = 5V$ | ±2 | ±6 | ±6 | % |
| | (Note 4) | | Mode 1 | e 1 | | | | |
| | | | | $V_{pin12} = 0V$ $f_{CLK} = 500$ kHz | ±2 | ±6 | ±6 | % |
| H _{OLP} | DC Lowpass Gain | | Mode 1 R1 = | R2 = 10k | 0 | ±0.2 | ±0.2 | dB |
| V _{OS1} | DC Offset Voltage (Note 5) | | | | ±5.0 | ±20 | ±20 | mV |
| V _{OS2} | DC Offset Voltage | Min | $V_{pin12} = +5V$ | $S_{A/B} = V^+$ | -150 | -185 | -185 | mV |

Electrical Characteristics (Continued)

 $V^{+} = +5.00V$ and V^{-}

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Logic Input Characteristics (Continued)

Boldface limits apply for T_{MIN} to T_{MAX} ; all other limits $T_A = T_J = 25$ °C

| | | | MF | | | |
|-----------|-----------------|-------------------------|-------------------------|----------|-----------|-------|
| Parameter | | | | | | |
| | | Conditions | s Typical Tested Design | | Design | Units |
| | | | (Note 8) | Limit | Limit | |
| | | | | (Note 9) | (Note 10) | |
| | Min Logical "1" | $V^+ = +10V, V^- = 0V,$ | | +2.0 | +2.0 | V |
| | Max Logical "0" | $V_{LSh} = 0V$ | | +0.8 | +0.8 | V |

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications do not apply when operating the device beyond its specified operating conditions.

Note 2: When the input voltage (V_{IN}) at any pin exceeds the power supply rails $(V_{IN} < V^-)$ or $V_{IN} > V^+)$ the absolute value of current at that pin should be limited to 5 mA or less. The 20 mA package input current limits the number of pins that can exceed the power supply boundaries with a 5 mA current limit to four.

Note 3: The maximum power dissipation must be derated at elevated temperatures and is dictated by T_{JMAX} , θ_{JA} , and the ambient temperature, T_A . The maximum allowable power dissipation at any temperature is $P_D = (T_{JMAX} - T_A)/\theta_{JA}$ or the number given in the Absolute Maximum Ratings, whichever is lower. For this device, $T_{JMAX} = 125^{\circ}C$, and the typical junction-to-ambient thermal resistance of the MF10ACN/CCN when board mounted is 55°C/W. For the MF10AJ/CCJ, this number increases to 95°C/W and for the MF10ACWM/CCWM this number is 66°C/W.

Note 4: The accuracy of the Q value is a function of the center frequency (f_O). This is illustrated in the curves under the heading "Typical Performance Characteristics".

Note 5: V_{OS1}, V_{OS2}, and V_{OS3} refer to the internal offsets as discussed in the Applications Information Section 3.4.

Note 6: For \pm 5V supplies the dynamic range is referenced to 2.82V rms (4V peak) where the wideband noise over a 20 kHz bandwidth is typically 200 μ V rms for the MF10 with a 50:1 CLK ratio and 280 μ V rms for the MF10 with a 100:1 CLK ratio.

Note 7: The short circuit source current is measured by forcing the output that is being tested to its maximum positive voltage swing and then shorting that output to the negative supply. The short circuit sink current is measured by forcing the output that is being tested to its maximum negative voltage swing and then shorting that output to the positive supply. These are the worst case conditions.

Note 8: Typicals are at 25°C and represent most likely parametric norm.

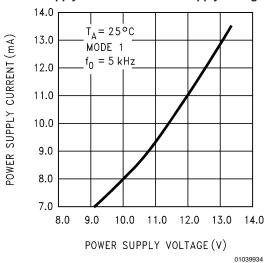
Note 9: Tested limits are guaranteed to National's AOQL (Average Outgoing Quality Level).

Note 10: Design limits are guaranteed but not 100% tested. These limits are not used to calculate outgoing quality levels.

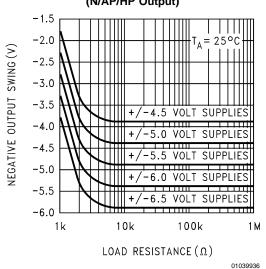
Note 11: Human body model, 100 pF discharged through a 1.5 k Ω resistor.

Typical Performance Characteristics

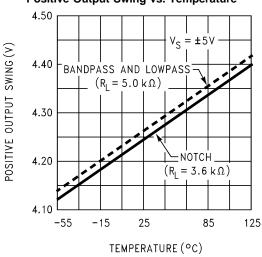
Power Supply Current vs. Power Supply Voltage



Negative Output Voltage Swing vs. Load Resistance (N/AP/HP Output)



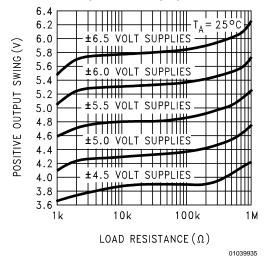
Positive Output Swing vs. Temperature



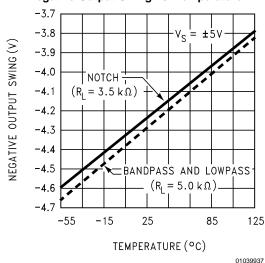
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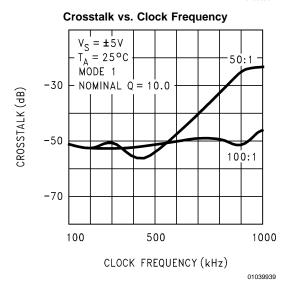
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Positive Output Voltage Swing vs. Load Resistance (N/AP/HP Output)

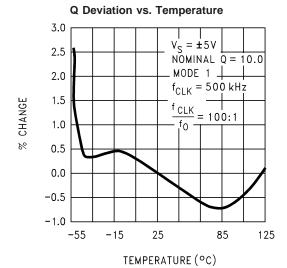


Negative Output Swing vs. Temperature





Typical Performance Characteristics (Continued)



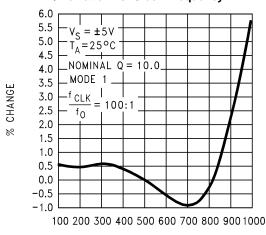
Q Deviation vs. Clock Frequency

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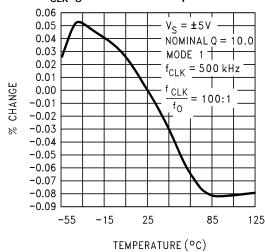
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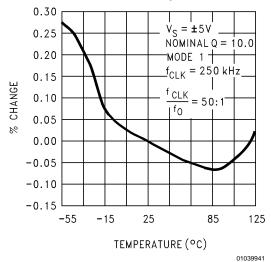


f_{CLK}/f_O Deviation vs. Temperature

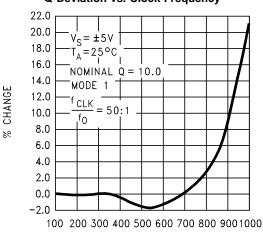
CLOCK FREQUENCY (kHz)



Q Deviation vs. Temperature



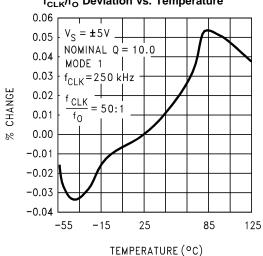
Q Deviation vs. Clock Frequency



CLOCK FREQUENCY (kHz)

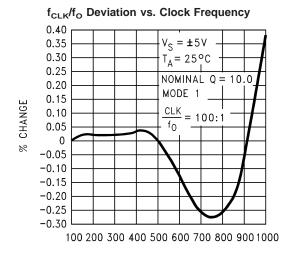
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Typical Performance Characteristics (Continued)

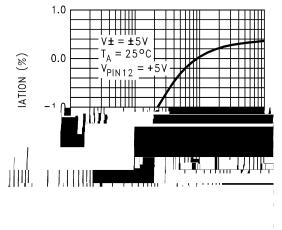


CLOCK FREQUENCY (kHz)

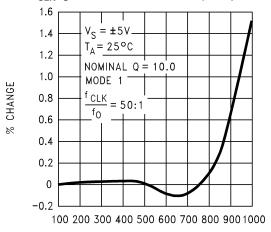
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Deviation of f_{CLK}/f_O vs. Nominal Q



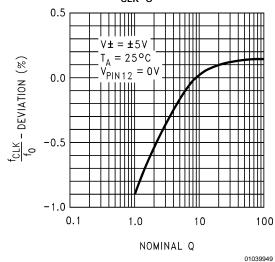
f_{CLK}/f_O Deviation vs. Clock Frequency



CLOCK FREQUENCY (kHz)

01039947

Deviation of $f_{\text{CLK}} / f_{\text{O}}$ vs. Nominal Q



Pin Descriptions

LP(1,20), BP(2,19), N/AP/HP(3,18)

The second order lowpass, bandpass and notch/allpass/highpass outputs. These outputs can typically sink 1.5 mA and source 3 mA. Each output typically swings to within 1V of each supply.

INV(4,17) The inverting input of the summing

op-amp of each filter. These are high impedance inputs, but the non-inverting input is internally tied to AGND, making INV_A and INV_B behave like summing junctions (low impedance, current

inputs).

S1 (5,16) S1 is a signal input pin used in the allpass filter configurations (see modes

4 and 5). The pin should be driven with a source impedance of less than 1 k Ω . If S1 is not driven with a signal it should

be tied to AGND (mid-supply).

S_{A/B}(6) This pin activates a switch that con-

nects one of the inputs of each filter's second summer to either AGND ($S_{A/B}$ tied to V^-) or to the lowpass (LP) output ($S_{A/B}$ tied to V^+). This offers the flexibility needed for configuring the filter in its

various modes of operation.

 $V_A^+(7), V_D^+(8)$ Analog positive supply and digital posi-

tive supply. These pins are internally connected through the IC substrate and therefore V_A^+ and V_D^+ should be derived from the same power supply source. They have been brought out separately so they can be bypassed by separate capacitors, if desired. They

 $\textbf{H}_{\textbf{OLP}}\text{:}$ the gain (in V/V) of the lowpass output as f \rightarrow 0 Hz (Figure 2).

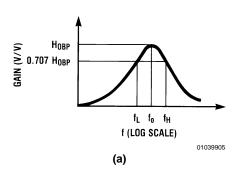
 $\textbf{H}_{\textbf{OHP}}\text{:}$ the gain (in V/V) of the highpass output as f \rightarrow f_{CLK}/2 (Figure 3).

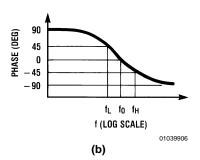
 $extbf{H}_{ extbf{ON}}$: the gain (in V/V) of the notch output as f o 0 Hz and as $f o f_{ extbf{CLK}}/2$, when the notch filter has equal gain above and

below the center frequency (*Figure 4*). When the low-frequency gain differs from the high-frequency gain, as in modes 2 and 3a (*Figure 11* and *Figure 8*), the two quantities below are used in place of H_{ON}.

 $\textbf{H}_{\textbf{ON1}}\textbf{:}$ the gain (in V/V) of the notch output as $f\to 0$ Hz.

 $\mathbf{H_{ON2}}$: the gain (in V/V) of the notch output as f \rightarrow f_{CLK}/2.

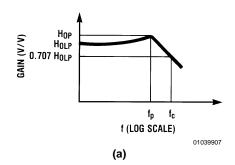


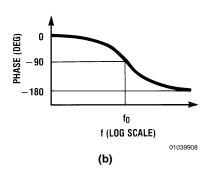


$$\begin{split} & \textbf{H}_{BP}(\textbf{s}) = \frac{\textbf{H}_{OBP} \frac{\omega \textbf{O}}{\textbf{Q}} \, \textbf{S}}{\textbf{s}^2 + \frac{\textbf{s}\omega_{\textbf{O}}}{\textbf{Q}} + \, \omega_{\textbf{O}}^2} \\ & \textbf{Q} = \frac{\textbf{f}_{\textbf{O}}}{\textbf{f}_{\textbf{H}} - \textbf{f}_{\textbf{L}}}; \,\, \textbf{f}_{\textbf{O}} = \sqrt{\textbf{f}_{\textbf{L}}\textbf{f}_{\textbf{H}}} \\ & \textbf{f}_{\textbf{L}} = \textbf{f}_{\textbf{O}} \left(\frac{-1}{2\textbf{Q}} + \sqrt{\left(\frac{1}{2\textbf{Q}}\right)^2 + 1} \,\,\right) \\ & \textbf{f}_{\textbf{H}} = \textbf{f}_{\textbf{O}} \left(\frac{1}{2\textbf{Q}} + \sqrt{\left(\frac{1}{2\textbf{Q}}\right)^2 + 1} \,\,\right) \\ & \omega_{\textbf{O}} = 2\pi\textbf{f}_{\textbf{O}} \end{split}$$

FIGURE 1. 2nd-Order Bandpass Response

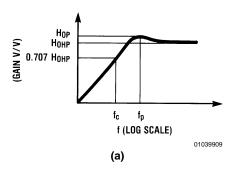
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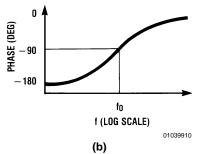




$$\begin{split} & \textbf{H}_{LP}(\textbf{s}) = \frac{\textbf{H}_{OLP}\omega_{O}^{2}}{\textbf{s}^{2} + \frac{\textbf{s}\omega_{O}}{Q} + \omega_{O}^{2}} \\ & \textbf{f}_{C} = \textbf{f}_{O} \times \sqrt{\left(1 - \frac{1}{2Q^{2}}\right) + \sqrt{\left(1 - \frac{1}{2Q^{2}}\right)^{2} + 1}} \\ & \textbf{f}_{p} = \textbf{f}_{O} \sqrt{1 - \frac{1}{2Q^{2}}} \\ & \textbf{H}_{OP} = \textbf{H}_{OLP} \times \frac{1}{\frac{1}{Q}\sqrt{1 - \frac{1}{4Q^{2}}}} \end{split}$$

FIGURE 2. 2nd-Order Low-Pass Response





$$H_{HP}(s) = \frac{H_{OHP}s^2}{s^2 + \frac{s\omega_O}{Q} + \omega_O^2}$$

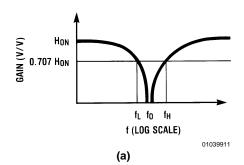
$$f_C = f_O \times \left[\sqrt{\left(1-\frac{1}{2Q^2}\right) + \sqrt{\left(1-\frac{1}{2Q^2}\right)^2 + 1}}\,\right]^{-1}$$

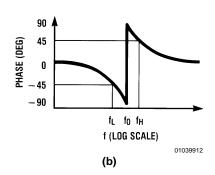
$$\mathfrak{f}_p=\mathfrak{f}_0\times\left[\sqrt{1-\frac{1}{2Q^2}}\right]^{-1}$$

$$H_{OP} = H_{OHP} \times \frac{1}{\frac{1}{Q}\sqrt{1 - \frac{1}{4Q^2}}}$$

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FIGURE 3. 2nd-Order High-Pass Response

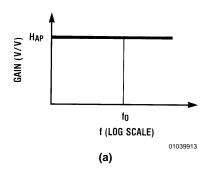


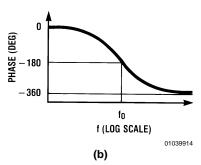


$$\begin{split} &H_{\text{N}}(s) = \frac{H_{\text{ON}}(s^2 + \omega_{\text{O}}^2)}{s^2 + \frac{s\omega_{\text{O}}}{Q} + \omega_{\text{O}}^2} \\ &Q = \frac{f_{\text{O}}}{f_{\text{H}} - f_{\text{L}}}; \; f_{\text{O}} = \sqrt{f_{\text{L}} \, f_{\text{H}}} \\ &f_{\text{L}} = f_{\text{O}} \left(\frac{-1}{2Q} + \sqrt{\left(\frac{1}{2Q} \right)^2 + 1} \; \right) \\ &f_{\text{H}} = f_{\text{O}} \left(\frac{1}{2Q} + \sqrt{\left(\frac{1}{2Q} \right)^2 + 1} \; \right) \end{split}$$

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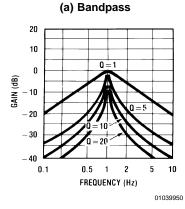
FIGURE 4. 2nd-Order Notch Response

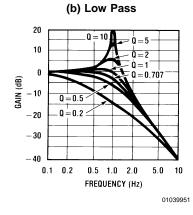


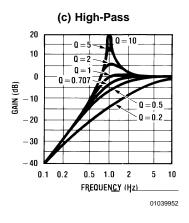


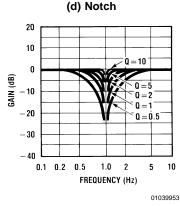
$$H_{AP}(s) = \frac{H_{OAP}\left(s^2 - \frac{s\omega_{O}}{Q} + \omega_{O}^2\right)}{s^2 + \frac{s\omega_{O}}{Q} + \omega_{O}^2}$$

FIGURE 5. 2nd-Order All-Pass Response









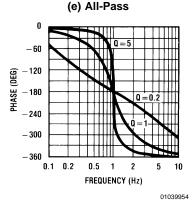


FIGURE 6. Response of various 2nd-order filters as a function of Q. Gains and center frequencies are normalized to unity.

2.0 Modes of Operation

The MF10 is a switched capacitor (sampled data) filter. To fully describe its transfer functions, a time domain approach is appropriate. Since this is cumbersome, and since the MF10 closely approximates continuous filters, the following discussion is based on the well known frequency domain. Each MF10 can produce a full 2nd order function. See *Table 1* for a summary of the characteristics of the various modes.

MODE 1: Notch 1, Bandpass, Lowpass Outputs:

 f_O = center frequency of the complex pole pair

$$=\frac{f_{CLK}}{100} \text{ or } \frac{f_{CLK}}{50}$$

 f_{notch} = center frequency of the imaginary zero pair = f_{o} .

$$H_{OLP} = Lowpass gain (as f \rightarrow 0) = -\frac{R2}{R1}$$

$$H_{OBP} = Bandpass gain (at f = f_O) = -\frac{R3}{R1}$$

$$H_{ON} = Notch output gain as \begin{cases} f \rightarrow 0 \\ f \rightarrow f_{CLK}/2 \end{cases} = \frac{-R_2}{R_1}$$

$$Q = \frac{f_0}{BW} = \frac{R3}{R2}$$

= quality factor of the complex pole pair
 BW = the −3 dB bandwidth of the bandpass output.
 Circuit dynamics:

$$\begin{split} H_{OLP} &= \frac{H_{OBP}}{Q} \, \text{or} \, H_{OBP} = H_{OLP} \times Q \\ &= H_{ON} \times Q. \\ H_{OLP(peak)} &\cong Q \times H_{OLP} \, (\text{for high Q's}) \end{split}$$

MODE 1a: Non-Inverting BP, LP (See Figure 8)

$$f_{O} = \frac{f_{CLK}}{100} \text{ or } \frac{f_{CLK}}{50}$$

$$Q = \frac{R3}{R2}$$

$$H_{OLP} = -1; H_{OLP(peak)} \cong Q \times H_{OLP} \text{ (for high Q's)}$$

$$H_{OBP_1} = -\frac{R3}{R2}$$

$$H_{OBP_2} = 1 \text{ (Non-Inverting)}$$

Note: $V_{\mbox{\footnotesize{IN}}}$ should be driven from a low impedance (<1 $\mbox{\footnotesize{k}}\Omega)$ source.

Circuit Dynamics: H_{OBP1} = Q

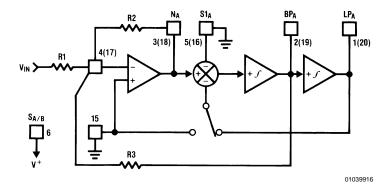


FIGURE 7. MODE 1

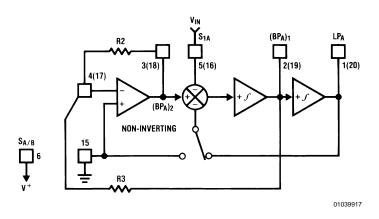


FIGURE 8. MODE 1a

MODE 2: Notch 2, Bandpass, Lowpass: $f_{notch} < f_{O}$ (See *Figure 9*)

$$f_{O} = \text{center frequency}$$

$$= \frac{f_{CLK}}{100} \sqrt{\frac{R2}{R4} + 1} \text{ or } \frac{f_{CLK}}{50} \sqrt{\frac{R2}{R4} + 1}$$

$$f_{notch} = \frac{f_{CLK}}{100} \text{ or } \frac{f_{CLK}}{50}$$

$$Q = \text{quality factor of the complex pole pair}$$

$$= \frac{\sqrt{\frac{R2}{R4} + 1}}{\frac{R2}{R3}}$$
Here = Lowers output gain (as f \rightarrow 0)

$$H_{OLP}$$
 = Lowpass output gain (as f \rightarrow 0)
= $-\frac{R2/R1}{R2/R4 + 1}$

$$H_{OBP}=$$
 Bandpass output gain (at f = f_O) = $-R3/R1$
 $H_{ON_1}=$ Notch output gain (as f \longrightarrow 0)
 $R2/R1$

$$H_{ON_2} = Notch$$
 output gain $\left(\text{as f} \rightarrow \frac{f_{CLK}}{2} \right) = -R2/R1$
Filter dynamics: $H_{OBP} = Q \sqrt{H_{OLP} H_{ON_2}} = \sqrt{H_{ON_1} H_{ON_2}}$

MODE 3: Highpass, Bandpass, Lowpass Outputs (See *Figure 10*)

$$\begin{split} f_O &= \frac{f_{CLK}}{100} \times \sqrt{\frac{R2}{R4}} \text{ or } \frac{f_{CLK}}{50} \times \sqrt{\frac{R2}{R4}} \\ Q &= \text{ quality factor of the complex pole pair} \\ &= \sqrt{\frac{R2}{R4}} \times \frac{R3}{R2} \\ H_{OHP} &= \text{ Highpass Gain } \left(\text{ as f} \to \frac{f_{CLK}}{2}\right) = -\frac{R2}{R1} \\ H_{OBP} &= \text{ Lowpass Gain } \left(\text{ at f} = f_O\right) = -\frac{R3}{R1} \\ H_{OLP} &= \text{ Lowpass Gain } \left(\text{ as f} \to 0\right) = -\frac{R4}{R1} \\ \text{Circuit dynamics: } \frac{R2}{R4} = \frac{H_{OHP}}{H_{OLP}}; \\ H_{OBP} &= \sqrt{H_{OHP} \times H_{OLP}} \times Q \\ H_{OLP(peak)} &\cong Q \times H_{OLP} \text{ (for high Q's)} \\ H_{OHP(peak)} &\cong Q \times H_{OHP} \text{ (for high Q's)} \end{split}$$

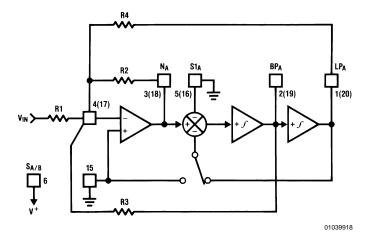
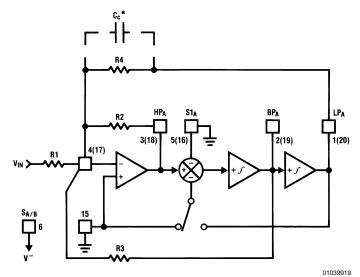


FIGURE 9. MODE 2



*In Mode 3, the feedback loop is closed around the input summing amplifier; the finite GBW product of this op amp causes a slight Q enhancement. If this is a problem, connect a small capacitor (10 pF – 100 pF) across R4 to provide some phase lead.

FIGURE 10. MODE 3

MODE 3a: HP, BP, LP and Notch with External Op Amp (See Figure 11)

$$\begin{split} &f_O &= \frac{f_{CLK}}{100} \times \sqrt{\frac{R2}{R4}} \text{ or } \frac{f_{CLK}}{50} \times \sqrt{\frac{R2}{R4}} \\ &Q &= \sqrt{\frac{R2}{R4}} \times \frac{R3}{R2} \\ &H_{OHP} = -\frac{R2}{R1} \\ &H_{OBP} = -\frac{R3}{R1} \\ &H_{OLP} = -\frac{R4}{R1} \\ &f_n &= \text{notch frequency} = \frac{f_{CLK}}{100} \sqrt{\frac{R_h}{R_l}} \text{ or } \frac{f_{CLK}}{50} \sqrt{\frac{R_h}{R_l}} \\ &H_{ON} = \text{gain of notch at} \\ &f = f_O = \left| \left| Q \left(\frac{R_g}{R_l} H_{OLP} - \frac{R_g}{R_h} H_{OHP} \right) \right| \right| \\ &H_{n1} &= \text{gain of notch (as } f \longrightarrow 0) = \frac{R_g}{R_l} \times H_{OLP} \\ &H_{n2} &= \text{gain of notch} \left(\text{as } f \longrightarrow \frac{f_{CLK}}{2} \right) \\ &= -\frac{R_g}{R_h} \times H_{OHP} \end{split}$$

MODE 4: Allpass, Bandpass, Lowpass Outputs(See Figure 12)

$$\begin{split} &f_O &= \text{center frequency} \\ &= \frac{f_{CLK}}{100} \text{ or } \frac{f_{CLK}}{50}; \\ &f_z{}^* = \text{center frequency of the complex zero} \approx f_O \\ &Q &= \frac{f_O}{BW} = \frac{R3}{R2}; \\ &Q_Z = \text{quality factor of complex zero pair } = \frac{R3}{R1} \\ &\text{For AP output make R1} = R2 \\ &H_{OAP}{}^* = \text{Allpass gain} \left(\text{at } 0 < f < \frac{f_{CLK}}{2} \right) = -\frac{R2}{R1} = -1 \\ &H_{OLP} = \text{Lowpass gain (as } f \longrightarrow 0) \\ &= -\left(\frac{R2}{R1} + 1 \right) = -2 \\ &H_{OBP} = \text{Bandpass gain (at } f = f_O) \\ &= -\frac{R3}{R2} \left(1 + \frac{R2}{R1} \right) = -2 \left(\frac{R3}{R2} \right) \\ &\text{Circuit Dynamics: } H_{OBP} = (H_{OLP}) \times Q = (H_{OAP} + 1)Q \end{split}$$

*Due to the sampled data nature of the filter, a slight mismatch of $\rm f_z$ and $\rm f_O$ occurs causing a 0.4 dB peaking around $\rm f_O$ of the allpass filter amplitude response (which theoretically should be a straight line). If this is unacceptable, Mode 5 is recommended.

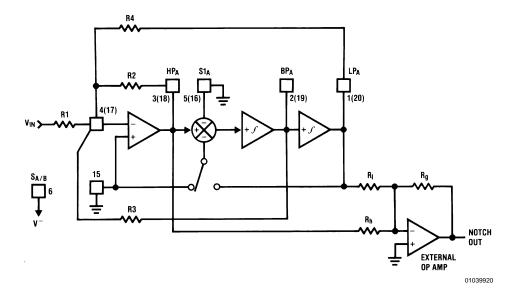


FIGURE 11. MODE 3a

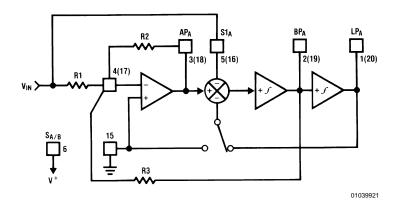


FIGURE 12. MODE 4

MODE 5: Numerator Complex Zeros, BP, LP (See Figure 13)

$$\begin{split} f_O &= \sqrt{1 + \frac{R2}{R4}} \times \frac{f_{CLK}}{100} \text{ or } \sqrt{1 + \frac{R2}{R4}} \times \frac{f_{CLK}}{50} \\ f_z &= \sqrt{1 - \frac{R2}{R4}} \times \frac{f_{CLK}}{100} \text{ or } \sqrt{1 - \frac{R1}{R4}} \times \frac{f_{CLK}}{50} \\ Q &= \sqrt{1 + R2/R4} \times \frac{R3}{R2} \\ Q_Z &= \sqrt{1 - R1/R4} \times \frac{R3}{R1} \end{split}$$

$$\begin{array}{ll} H_{0z1} &= \text{gain at C.Z. output (as f} \longrightarrow 0 \text{ Hz)} \\ & \frac{-\text{R2}(\text{R4} - \text{R1})}{\text{R1}(\text{R2} + \text{R4})} \\ H_{0z2} &= \text{gain at C.Z. output } \left(\text{as f} \longrightarrow \frac{f_{\text{CLK}}}{2} \right) = \frac{-\text{R2}}{\text{R1}} \\ H_{\text{OBP}} &= -\left(\frac{\text{R2}}{\text{R1}} + 1 \right) \times \frac{\text{R3}}{\text{R2}} \\ H_{\text{OLP}} &= -\left(\frac{\text{R2} + \text{R1}}{\text{R2} + \text{R4}} \right) \times \frac{\text{R4}}{\text{R1}} \end{array}$$

MODE 6a: Single Pole, HP, LP Filter (See Figure 14)

$$\begin{array}{l} f_{\text{C}} &= \text{ cutoff frequency of LP or HP output} \\ &= \frac{R2}{R3} \, \frac{f_{\text{CLK}}}{100} \text{ or } \frac{R2}{R3} \, \frac{f_{\text{CLK}}}{50} \\ \\ H_{\text{OLP}} &= -\frac{R3}{R1} \\ \\ H_{\text{OHP}} &= -\frac{R2}{R1} \end{array}$$

MODE 6b: Single Pole LP Filter (Inverting and Non-Inverting) (See *Figure 15*)

$$\begin{array}{ll} f_{\text{C}} &= \text{ cutoff frequency of LP outputs} \\ &\cong \frac{R2}{R3} \, \frac{f_{\text{CLK}}}{100} \text{ or } \frac{R2}{R3} \, \frac{f_{\text{CLK}}}{50} \\ \\ H_{\text{OLP1}} &= 1 \text{ (non-inverting)} \\ H_{\text{OLP2}} &= -\frac{R3}{R2} \end{array}$$

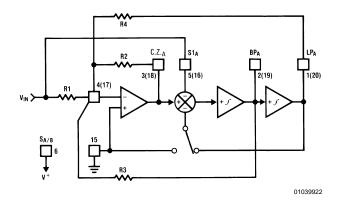


FIGURE 13. MODE 5

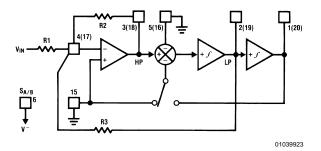
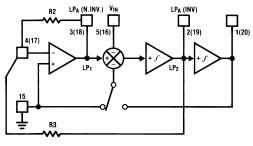


FIGURE 14. MODE 6a



01039924

FIGURE 15. MODE 6b

TABLE 1. Summary of Modes. Realizable filter types (e.g. low-pass) denoted by asterisks. Unless otherwise noted, gains of various filter outputs are inverting and adjustable by resistor ratios.

| Mode | BP | LP | НР | N | AP | Number of | Adjustable | Notes |
|------|------------------------|-----------------------------|----|---|----|-----------|----------------------------------|---------------------------------------|
| | | | | | | Resistors | f _{CLK} /f _O | |
| 1 | * | * | | * | | 3 | No | |
| | (2) | | | | | | | May need input buffer. |
| 1a | $H_{OBP1} = -Q$ | H _{OLP} + 1 | | | | 2 | No | Poor dynamics for |
| | H _{OBP2} = +1 | | | | | | | high Q. |
| 2 | * | * | | * | | 3 | Yes (above f _{CLK} /50 | |
| | | | | | | | or f _{CLK} /100) | |
| 3 | * | * | * | | | 4 | Yes | Universal State-Variable |
| 3 | | | | | | | | Filter. Best general-purpose mode. |
| 3a | * | * | * | * | | 7 | Yes | As above, but also includes |
| Sa | | | | | | | | resistor-tuneable notch. |
| 4 | * | * | | | * | 3 | No | Gives Allpass response with |
| | | | | | | | | $H_{OAP} = -1$ and $H_{OLP} = -2$. |
| 5 | * | * | | | * | 4 | | Gives flatter allpass response |
| | | | | | | | | than above if $R_1 = R_2 = 0.02R_4$. |
| 6a | | * | * | | | 3 | | Single pole. |
| 6b | | (2) | | | | 2 | | Single pole. |
| | | $H_{OLP1} = +1$ | | | | | | |
| | | $H_{OLP2} = \frac{-R3}{R2}$ | | | | | | |
| | | HZ | | | | | | |

The MF10 is a general-purpose dual second-order state variable filter whose center frequency is proportional to the frequency of the square wave applied to the clock input ($f_{\rm CLK}$). By connecting pin 12 to the appropriate DC voltage, the filter center frequency $f_{\rm O}$ can be made equal to either $f_{\rm CLK}/100$ or $f_{\rm CLK}/50$. $f_{\rm O}$ can be very accurately set (within ±6%) by using a crystal clock oscillator, or can be easily varied over a wide frequency range by adjusting the clock frequency. If desired, the $f_{\rm CLK}/f_{\rm O}$ ratio can be altered by external resistors as in *Figures 9, 10, 11, 13, 14, 15*. The filter Q and gain are determined by external resistors.

All of the five second-order filter types can be built using either section of the MF10. These are illustrated in *Figure 1* through *Figure 5* along with their transfer functions and some related equations. *Figure 6* shows the effect of Q on the shapes of these curves. When filter orders greater than two are desired, two or more MF10 sections can be cascaded.

3.1 DESIGN EXAMPLE

In order to design a second-order filter section using the MF10, we must define the necessary values of three parameters: f_0 , the filter section's center frequency; H_0 , the passband gain; and the filter's Q. These are determined by the characteristics required of the filter being designed.

As an example, let's assume that a system requires a fourth-order Chebyshev low-pass filter with 1 dB ripple, unity gain at DC, and 1000 Hz cutoff frequency. As the system order is four, it is realizable using both second-order sections of an MF10. Many filter design texts include tables that list the characteristics (f_O and Q) of each of the second-order filter sections needed to synthesize a given higher-order filter. For the Chebyshev filter defined above, such a table yields the following characteristics:

$$f_{OA} = 529 \text{ Hz } Q_A = 0.785$$

$$f_{OB} = 993 \text{ Hz } Q_B = 3.559$$

For unity gain at DC, we also specify:

$$H_{OA} = 1$$

$$H_{OB} = 1$$

The desired clock-to-cutoff-frequency ratio for the overall filter of this example is 100 and a 100 kHz clock signal is available. Note that the required center frequencies for the two second-order sections will not be obtainable with clock-to-center-frequency ratios of 50 or 100. It will be necessary to adjust

externally. From *Table 1*, we see that Mode 3 can be used to produce a low-pass filter with resistor-adjustable center frequency.

In most filter designs involving multiple second-order stages, it is best to place the stages with lower Q values ahead of stages with higher Q, especially when the higher Q is greater than 0.707. This is due to the higher relative gain at the center frequency of a higher-Q stage. Placing a stage with lower Q ahead of a higher-Q stage will provide some attenuation at the center frequency and thus help avoid clipping of signals near this frequency. For this example, stage A has the lower Q (0.785) so it will be placed ahead of the other stage.

For the first section, we begin the design by choosing a convenient value for the input resistance: $R_{1A} = 20k$. The absolute value of the passband gain H_{OLPA} is made equal to 1 by choosing R_{4A} such that: $R_{4A} = -H_{OLPA}R_{1A} = R_{1A} = 20k$. If the 50/100/CL pin is connected to mid-supply for nominal 100:1 clock-to-center-frequency ratio, we find R_{2A} by:

$$\begin{split} R_{2A} &= R_{4A} \frac{f_{0A}^2}{(f_{CLK}/100)^2} = 2 \times 10^4 \times \frac{(529)^2}{(1000)^2} = 5.6 \text{k and} \\ R_{3A} &= Q_A \sqrt{R_{2A}R_{4A}} = 0.785 \sqrt{5.6 \times 10^3 \times 2 \times 10^4} = 8.3 \text{k} \end{split}$$

The resistors for the second section are found in a similar fashion:

$$\begin{split} R_{1B} &= 20k \\ R_{4B} &= R_{1B} = 20k \\ R_{2B} &= R_{4B} \frac{f_{0B}^2}{(f_{CLK}/100)^2} = 20k \frac{(993)^2}{(1000)^2} = 19.7k \\ R_{3B} &= Q_B \sqrt{R_{2B}R_{4B}} = 3.559\sqrt{1.97 \times 10^4 \times 2 \times 10^4} = 70.6k \end{split}$$

The complete circuit is shown in *Figure 16* for split ±5V power supplies. Supply bypass capacitors are highly recommended.

3.0 Applications Information (Continued)

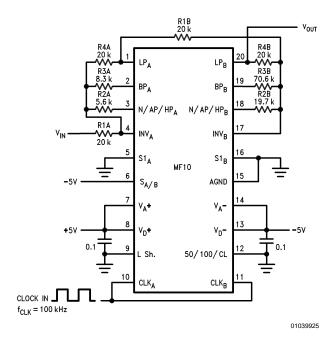
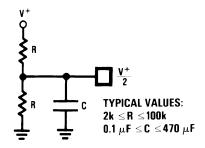
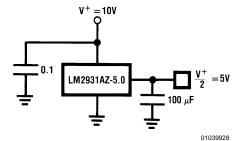


FIGURE 16. Fourth-Order Chebyshev Low-Pass Filter from Example in 3.1.

3.0 Applications Information (Continued)



(a) Resistive Divider with Decoupling Capacitor



(b) Voltage Regulator

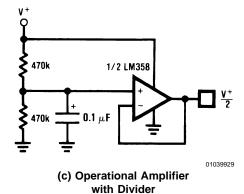


FIGURE 18. Three Ways of Generating V*/2 for Single-Supply Operation

(Continued)

3.2 SINGLE SUPPLY OPERATION

The MF10 can also operate with a single-ended power supply. Figure 17 shows the example filter with a single-ended power supply. V_A^+ and V_D^+ are again connected to the positive power supply (8V to 14V), and V_A^- and V_D^- are connected to ground. The A_{GND} pin must be tied to V+/2 for single supply operation. This half-supply point should be very "clean", as any noise appearing on it will be treated as an input to the filter. It can be derived from the supply voltage with a pair of resistors and a bypass capacitor (Figure 18a), or a low-impedance half-supply voltage can be made using a three-terminal voltage regulator or an operational amplifier (Figure 18b and Figure 18c). The passive resistor divider with a bypass capacitor is sufficient for many applications, provided that the time constant is long enough to reject any power supply noise. It is also important that the half-supply reference present a low impedance to the clock frequency, so at very low clock frequencies the regulator or op-amp approaches may be preferable because they will require smaller capacitors to filter the clock frequency. The main power supply voltage should be clean (preferably regulated) and bypassed with 0.1 µF.

3.3 DYNAMIC CONSIDERATIONS

The maximum signal handling capability of the MF10, like that of any active filter, is limited by the power supply voltages used. The amplifiers in the MF10 are able to swing to within about 1V of the supplies, so the input signals must be kept small enough that none of the outputs will exceed these limits. If the MF10 is operating on ±5V, for example, the outputs will clip at about 8 V_{p-p} . The maximum input voltage multiplied by the filter gain should therefore be less than 8 V_{p-p}.

Note that if the filter Q is high, the gain at the lowpass or highpass outputs will be much greater than the nominal filter gain (Figure 6). As an example, a lowpass filter with a Q of 10 will have a 20 dB peak in its amplitude response at f_o. If the nominal gain of the filter HOLP is equal to 1, the gain at fo will be 10. The maximum input signal at fo must therefore be less than 800 mV_{p-p} when the circuit is operated on $\pm 5V$ supplies.

Also note that one output can have a reasonable small voltage on it while another is saturated. This is most likely for a circuit such as the notch in Mode 1 (Figure 7). The notch output will be very small at fo, so it might appear safe to apply a large signal to the input. However, the bandpass will have its maximum gain at fo and can clip if overdriven. If one output clips, the performance at the other outputs will be degraded, so avoid overdriving any filter section, even ones whose outputs are not being directly used. Accompanying Figure 7 through Figure 15 are equations labeled "circuit dynamics", which relate the Q and the gains at the various outputs. These should be consulted to determine peak circuit gains and maximum allowable signals for a given applica-

3.4 OFFSET VOLTAGE

The MF10's switched capacitor integrators have a higher equivalent input offset voltage than would be found in a typical continuous-time active filter integrator. Figure 19 shows an equivalent circuit of the MF10 from which the output DC offsets can be calculated. Typical values for these offsets with $S_{A/B}$ tied to V^+ are:

 V_{os1} = opamp offset = ±5 mV

 $V_{0s2} = -150 \text{ mV } @ 50:1:$ -300 mV @ 100:1

 $V_{os3} = -70 \text{ mV } @ 50:1:$ -140 mV @ 100:1

When $\rm S_{A/B}$ is tied to V^-, $\rm V_{os2}$ will approximately halve. The DC offset at the BP output is equal to the input offset of the lowpass integrator (V_{os3}). The offsets at the other outputs depend on the mode of operation and the resistor ratios, as described in the following expressions.

$$\begin{array}{ll} \textbf{Mode 1 and Mode 4} \\ \textbf{V}_{OS(N)} &= \textbf{V}_{OS1} \left(\frac{1}{Q} + 1 \left| \left| \textbf{H}_{OLP} \right| \right| \right) - \frac{\textbf{V}_{OS3}}{Q} \\ \end{array}$$

V_{OS(BP)}

 $= V_{OS(N)} - V_{OS2}$ V_{OS(LP)}

$$V_{OS}(N.INV.BP) = \left(1 + \frac{1}{Q}\right)V_{OS1} - \frac{V_{OS3}}{Q}$$

V_{OS}(INV.BP)

 $= V_{OS}(N.INV.BP) - V_{OS2}$ V_{OS(LP)}

(Continued)

Mode 2 and Mode 5

$$\begin{split} V_{OS(N)} &= \left(\frac{R2}{R_p} + 1\right) V_{OS1} \times \frac{1}{1 + R2/R4} \\ &+ V_{OS2} \frac{1}{1 + R4/R2} - \frac{V_{OS3}}{Q\sqrt{1 + R2/R4}} \\ &+ R_p = R1//R3//R4 \\ V_{OS(BP)} &= V_{OS3} \\ V_{OS(LP)} &= V_{OS(N)} - V_{OS2} \\ \textbf{Mode 3} \\ V_{OS(HP)} &= V_{OS2} \\ V_{OS(BP)} &= V_{OS1} \left[1 + \frac{R4}{R_p}\right] - V_{OS2} \left(\frac{R4}{R2}\right) \\ &- V_{OS3} \left(\frac{R4}{R3}\right) \\ &+ R_p = R1//R2//R3 \end{split}$$

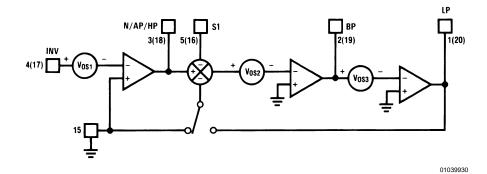


FIGURE 19. MF10 Offset Voltage Sources

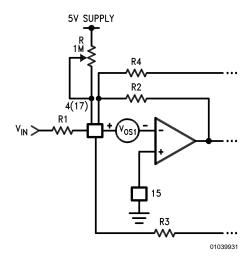


FIGURE 20. Method for Trimming V_{OS}

For most applications, the outputs are AC coupled and DC offsets are not bothersome unless large signals are applied

to the filter input. However, larger offset voltages will cause clipping to occur at lower AC signal levels, and clipping at

(Continued)

any of the outputs will cause gain nonlinearities and will change f_O and Q. When operating in Mode 3, offsets can become excessively large if R2 and R4 are used to make f_{CLK}/f_O significantly higher than the nominal value, especially if Q is also high. An extreme example is a bandpass filter having unity gain, a Q of 20, and $f_{CLK}/f_O = 250$ with pin 12 tied to ground (100:1 nominal). R4/R2 will therefore be equal to 6.25 and the offset voltage at the lowpass output will be about +1V. Where necessary, the offset voltage can be adjusted by using the circuit of *Figure 20*. This allows adjustment of V_{OS1} , which will have varying effects on the different outputs as described in the above equations. Some outputs cannot be adjusted this way in some modes, however $(V_{OS(BP)})$ in modes 1a and 3, for example).

3.5 SAMPLED DATA SYSTEM CONSIDERATIONS

The MF10 is a sampled data filter, and as such, differs in many ways from conventional continuous-time filters. An important characteristic of sampled-data systems is their effect on signals at frequencies greater than one-half the sampling frequency. (The MF10's sampling frequency is the same as its clock frequency.) If a signal with a frequency greater than one-half the sampling frequency is applied to the input of a sampled data system, it will be "reflected" to a frequency less than one-half the sampling frequency. Thus, an input signal whose frequency is $f_{\rm s}/2 + 100$ Hz will cause the system to respond as though the input frequency was $f_{\rm s}/2 - 100$ Hz. This phenomenon is known as "aliasing", and

can be reduced or eliminated by limiting the input signal spectrum to less than $f_{\rm s}/2$. This may in some cases require the use of a bandwidth-limiting filter ahead of the MF10 to limit the input spectrum. However, since the clock frequency is much higher than the center frequency, this will often not be necessary.

Another characteristic of sampled-data circuits is that the output signal changes amplitude once every sampling period, resulting in "steps" in the output voltage which occur at the clock rate (*Figure 21*). If necessary, these can be "smoothed" with a simple R–C low-pass filter at the MF10 output.

The ratio of f_{CLK} to f_{C} (normally either 50:1 or 100:1) will also affect performance. A ratio of 100:1 will reduce any aliasing problems and is usually recommended for wideband input signals. In noise sensitive applications, however, a ratio of 50:1 may be better as it will result in 3 dB lower output noise. The 50:1 ratio also results in lower DC offset voltages, as discussed in Section 3.4.

The accuracy of the f_{CLK}/f_O ratio is dependent on the value of Q. This is illustrated in the curves under the heading "Typical Performance Characteristics". As Q is changed, the true value of the ratio changes as well. Unless the Q is low, the error in f_{CLK}/f_O will be small. If the error is too large for a specific application, use a mode that allows adjustment of the ratio with external resistors.

It should also be noted that the product of Q and $\rm f_O$ should be limited to 300 kHz when $\rm f_O$ < 5 kHz, and to 200 kHz for $\rm f_O$ > 5 kHz.

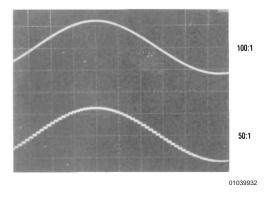
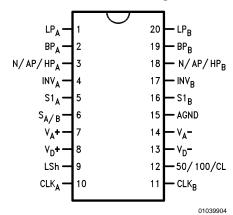


FIGURE 21. The Sampled-Data Output Waveform

3.0 Applications Information (Continued) **Connection Diagram**

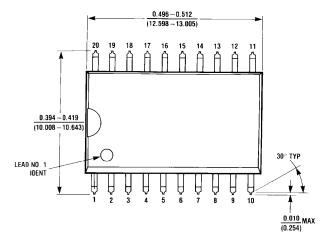
Surface Mount and Dual-In-Line Package

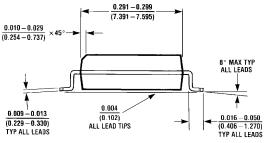


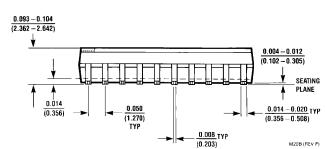
Top View
Order Number MF10CCWM
See NS Package Number M20B
Order Number MF10ACN or MF10CCN

See NS Package Number N20A

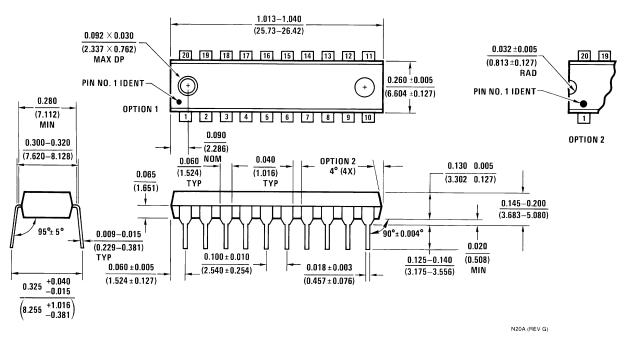
Physical Dimensions inches (millimeters) unless otherwise noted







Molded Package (Small Outline) (M) Order Number MF10ACWM or MF10CCWM **NS Package Number M20B**



20-Lead Molded Dual-In-Line Package (N) Order Number MF10ACN or MF10CCN **NS Package Number N20A**

Notes

LIFE SUPPORT POLICY

NATIONAL'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF THE PRESIDENT AND GENERAL COUNSEL OF NATIONAL SEMICONDUCTOR CORPORATION. As used herein:

- 1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
- 2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



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